Tossing coins, matching points and shifting Brownian motion

## Peter Mörters


based on joint work with

Günter Last (Karlsruhe)
Hermann Thorisson (Reykjavik)

## Setup of the talk

- Three problems in probability
- Solution of the extra head problem
- Solution of the Poisson matching problem
- Solution of the embedding problem for Brownian motion


## Problem 1: The extra head problem

Let $\left(X_{i}: i \in \mathbb{Z}\right)$ be a two sided sequence of independent fair coin tosses, i.e.

$$
\mathbb{P}\left\{X_{i}=\text { head }\right\}=\frac{1}{2}=\mathbb{P}\left\{X_{i}=\text { tail }\right\}
$$

Problem: Find a coin that landed heads so that all other coins are still independent with heads probability $\frac{1}{2}$ !

## Problem 1: The extra head problem

Let $\left(X_{i}: i \in \mathbb{Z}\right)$ be a two sided sequence of independent fair coin tosses, i.e.

$$
\mathbb{P}\left\{X_{i}=\text { head }\right\}=\frac{1}{2}=\mathbb{P}\left\{X_{i}=\text { tail }\right\}
$$

Problem: Find a coin that landed heads so that all other coins are still independent with heads probability $\frac{1}{2}$ !

Attempt: Turn the coin at zero. If it shows heads, fine. Otherwise look at the next coin to its right. Continue until you find a coin showing heads.

## Problem 1: The extra head problem

Let $\left(X_{i}: i \in \mathbb{Z}\right)$ be a two sided sequence of independent fair coin tosses, i.e.

$$
\mathbb{P}\left\{X_{i}=\text { head }\right\}=\frac{1}{2}=\mathbb{P}\left\{X_{i}=\text { tail }\right\}
$$

Problem: Find a coin that landed heads so that all other coins are still independent with heads probability $\frac{1}{2}$ !

Attempt: Turn the coin at zero. If it shows heads, fine. Otherwise look at the next coin to its right. Continue until you find a coin showing heads. Not good because: The probability that the coin to the left of the found coin has landed tails is

$$
\frac{1}{2} \times \frac{1}{2}+\frac{1}{2}=\frac{3}{4}
$$

## Problem 1: The extra head problem

Let $\left(X_{i}: i \in \mathbb{Z}\right)$ be a two sided sequence of independent fair coin tosses, i.e.

$$
\mathbb{P}\left\{X_{i}=\text { head }\right\}=\frac{1}{2}=\mathbb{P}\left\{X_{i}=\text { tail }\right\}
$$

Problem: Find a coin that landed heads so that all other coins are still independent with heads probability $\frac{1}{2}$ !

Attempt: Turn the coin at zero. If it shows heads, fine. Otherwise look at the next coin to its right. Continue until you find a coin showing heads.
Not good because: The probability that the coin to the left of the found coin has landed tails is

$$
\frac{1}{2} \times \frac{1}{2}+\frac{1}{2}=\frac{3}{4}
$$

Thorisson (1996) A solution exists if additional randomness can be used.

## Problem 1: The extra head problem

Let $\left(X_{i}: i \in \mathbb{Z}\right)$ be a two sided sequence of independent fair coin tosses, i.e.

$$
\mathbb{P}\left\{X_{i}=\text { head }\right\}=\frac{1}{2}=\mathbb{P}\left\{X_{i}=\text { tail }\right\}
$$

Problem: Find a coin that landed heads so that all other coins are still independent with heads probability $\frac{1}{2}$ !

Attempt: Turn the coin at zero. If it shows heads, fine. Otherwise look at the next coin to its right. Continue until you find a coin showing heads.
Not good because: The probability that the coin to the left of the found coin has landed tails is

$$
\frac{1}{2} \times \frac{1}{2}+\frac{1}{2}=\frac{3}{4} .
$$

Thorisson (1996) A solution exists if additional randomness can be used. Liggett (2001) Explicit, nonrandomized solution (I'll show you later).

## Problem 2: Matching of Poisson points

Let $\mathcal{R}$ and $\mathcal{B}$ be two independent standard Poisson processes on $\mathbb{R}^{d}$, constituing a random pattern of red and blue points.

Problem: Find a shift-invariant matching of red and blue points that minimizes the tail probabilities of the typical distance of matched points!

## Problem 2: Matching of Poisson points

Let $\mathcal{R}$ and $\mathcal{B}$ be two independent standard Poisson processes on $\mathbb{R}^{d}$, constituing a random pattern of red and blue points.

Problem: Find a shift-invariant matching of red and blue points that minimizes the tail probabilities of the typical distance of matched points!

Holroyd, Pemantle, Peres and Schramm (2008)
Explicit procedure called stable matching (I'll show you later).

- In $d=1$ a stable matching procedure is optimal.
- In $d=2$ it is open whether stable matching is optimal. An optimal non-randomized solution was given by Timar (2009).
- $\ln d \geq 3$ stable matching is bad, and the problem is open.


## Problem 3: Shifting Brownian motion

Let $B=\left(B_{t}: t \in \mathbb{R}\right)$ be a standard Brownian motion on $\mathbb{R}$.

## Problem 3: Shifting Brownian motion

Let $B=\left(B_{t}: t \in \mathbb{R}\right)$ be a standard Brownian motion on $\mathbb{R}$.
Strong Markov property: If $T$ is a stopping time then $\left(B_{t+T}-B_{T}: t \geq 0\right)$ is a Brownian motion on $\mathbb{R}_{+}$and independent of $\left(B_{t}: t \leq T\right)$.


## Problem 3: Shifting Brownian motion

Let $B=\left(B_{t}: t \in \mathbb{R}\right)$ be a standard Brownian motion on $\mathbb{R}$.
Strong Markov property: If $T$ is a stopping time then $\left(B_{t+T}-B_{T}: t \geq 0\right)$ is a Brownian motion on $\mathbb{R}_{+}$and independent of $\left(B_{t}: t \leq T\right)$.


An unbiased shift of $B$ is a random time $T$, which is a function of $B$, such that $\left(B_{T+t}-B_{T}\right)_{t \in \mathbb{R}}$ is a Brownian motion independent of $B_{T}$.

## Problem 3: Shifting Brownian motion

Let $B=\left(B_{t}: t \in \mathbb{R}\right)$ be a standard Brownian motion on $\mathbb{R}$.
Strong Markov property: If $T$ is a stopping time then ( $B_{t+T}-B_{T}: t \geq 0$ ) is a Brownian motion on $\mathbb{R}_{+}$and independent of $\left(B_{t}: t \leq T\right)$.


An unbiased shift of $B$ is a random time $T$, which is a function of $B$, such that $\left(B_{T+t}-B_{T}\right)_{t \in \mathbb{R}}$ is a Brownian motion independent of $B_{T}$.

The following are not unbiased shifts:

- first hitting time of a level, or first exit time from an interval;
- fixed times $T \neq 0$.


## Problem 3: Shifting Brownian motion

Here is an example of an unbiased shift:
Let ( $L_{t}^{0}: t \geq 0$ ) be the local time of $B$ at zero, and $r>0$. Take

$$
T_{r}:=\inf \left\{t \geq 0: L_{t}^{0}=r\right\} .
$$



## Problem 3: Shifting Brownian motion

Here is an example of an unbiased shift:
Let ( $L_{t}^{0}: t \geq 0$ ) be the local time of $B$ at zero, and $r>0$. Take

$$
T_{r}:=\inf \left\{t \geq 0: L_{t}^{0}=r\right\} .
$$



Embedding problem: Given a probability measure $\nu$ find an unbiased shift $T$ such that $B_{T}$ has the distribution $\nu$.

## Problem 3: Shifting Brownian motion

Here is an example of an unbiased shift:
Let ( $L_{t}^{0}: t \geq 0$ ) be the local time of $B$ at zero, and $r>0$. Take

$$
T_{r}:=\inf \left\{t \geq 0: L_{t}^{0}=r\right\} .
$$



Embedding problem: Given a probability measure $\nu$ find an unbiased shift $T$ such that $B_{T}$ has the distribution $\nu$.

Last, M ,Thorisson (2012)
Explicit solution $T$ which is also a stopping time with optimal tail behaviour. Inspired by solutions to Problem 1 (Liggett) and 2 (Holroyd et al.).

## Liggett's solution of the extra head problem

We come back to the extra head problem.
Problem: In a biinfinite sequence of independent fair coins find a coin that landed heads so that all other coins are still independent fair coins!

## Liggett's solution of the extra head problem

We come back to the extra head problem.
Problem: In a biinfinite sequence of independent fair coins find a coin that landed heads so that all other coins are still independent fair coins!

Solution (Liggett 2001): If the coin at zero does not show heads, turn the next coin to its right until the number of heads and tails you have seen agrees. Pick the last coin you turned, which automatically shows heads.


## Liggett's solution of the extra head problem

We come back to the extra head problem.
Problem: In a biinfinite sequence of independent fair coins find a coin that landed heads so that all other coins are still independent fair coins!

Solution (Liggett 2001): If the coin at zero does not show heads, turn the next coin to its right until the number of heads and tails you have seen agrees. Pick the last coin you turned, which automatically shows heads.


## Liggett's solution of the extra head problem

We come back to the extra head problem.
Problem: In a biinfinite sequence of independent fair coins find a coin that landed heads so that all other coins are still independent fair coins!

Solution (Liggett 2001): If the coin at zero does not show heads, turn the next coin to its right until the number of heads and tails you have seen agrees. Pick the last coin you turned, which automatically shows heads.


## Liggett's solution of the extra head problem

We come back to the extra head problem.
Problem: In a biinfinite sequence of independent fair coins find a coin that landed heads so that all other coins are still independent fair coins!

Solution (Liggett 2001): If the coin at zero does not show heads, turn the next coin to its right until the number of heads and tails you have seen agrees. Pick the last coin you turned, which automatically shows heads.


## Liggett's solution of the extra head problem

We come back to the extra head problem.
Problem: In a biinfinite sequence of independent fair coins find a coin that landed heads so that all other coins are still independent fair coins!

Solution (Liggett 2001): If the coin at zero does not show heads, turn the next coin to its right until the number of heads and tails you have seen agrees. Pick the last coin you turned, which automatically shows heads.


## Liggett's solution of the extra head problem

We come back to the extra head problem.
Problem: In a biinfinite sequence of independent fair coins find a coin that landed heads so that all other coins are still independent fair coins!

Solution (Liggett 2001): If the coin at zero does not show heads, turn the next coin to its right until the number of heads and tails you have seen agrees. Pick the last coin you turned, which automatically shows heads.


## Liggett's solution of the extra head problem

We come back to the extra head problem.
Problem: In a biinfinite sequence of independent fair coins find a coin that landed heads so that all other coins are still independent fair coins!

Solution (Liggett 2001): If the coin at zero does not show heads, turn the next coin to its right until the number of heads and tails you have seen agrees. Pick the last coin you turned, which automatically shows heads.


## Liggett's solution of the extra head problem

Why is this true?

- Use the sequence of coins to build a random walk.



## Liggett's solution of the extra head problem

Why is this true?

- Use the sequence of coins to build a random walk.

- Shifting the chosen coin to the origin means shifting the random walk by exactly one excursion.


## Liggett's solution of the extra head problem

Why is this true?

- Use the sequence of coins to build a random walk.

- Shifting the chosen coin to the origin means shifting the random walk by exactly one excursion.
- Reversing a random walk excursion leaves its distribution invariant.


## The stable matching algorithm

Problem: Find a shift-invariant matching of red and blue points that minimizes the tail probabilities of the typical distance of matched points!

## The stable matching algorithm

Problem: Find a shift-invariant matching of red and blue points that minimizes the tail probabilities of the typical distance of matched points!

Stable matching algorithm:

- Match any pair of red and blue points that are nearest to each other.
- Remove matched points, and apply same procedure repeatedly.
- 
- 



## The stable matching algorithm

Problem: Find a shift-invariant matching of red and blue points that minimizes the tail probabilities of the typical distance of matched points!

Stable matching algorithm:

- Match any pair of red and blue points that are nearest to each other.
- Remove matched points, and apply same procedure repeatedly.



## The stable matching algorithm

Problem: Find a shift-invariant matching of red and blue points that minimizes the tail probabilities of the typical distance of matched points!

Stable matching algorithm:

- Match any pair of red and blue points that are nearest to each other.
- Remove matched points, and apply same procedure repeatedly.


## The stable matching algorithm

Problem: Find a shift-invariant matching of red and blue points that minimizes the tail probabilities of the typical distance of matched points!

Stable matching algorithm:

- Match any pair of red and blue points that are nearest to each other.
- Remove matched points, and apply same procedure repeatedly.



## The stable matching algorithm

Problem: Find a shift-invariant matching of red and blue points that minimizes the tail probabilities of the typical distance of matched points!

Stable matching algorithm:

- Match any pair of red and blue points that are nearest to each other.
- Remove matched points, and apply same procedure repeatedly.


## The stable matching algorithm

Problem: Find a shift-invariant matching of red and blue points that minimizes the tail probabilities of the typical distance of matched points!

Stable matching algorithm:

- Match any pair of red and blue points that are nearest to each other.
- Remove matched points, and apply same procedure repeatedly.


## The stable matching algorithm

Problem: Find a shift-invariant matching of red and blue points that minimizes the tail probabilities of the typical distance of matched points!

Stable matching algorithm:

- Match any pair of red and blue points that are nearest to each other.
- Remove matched points, and apply same procedure repeatedly.


## The stable matching algorithm

Problem: Find a shift-invariant matching of red and blue points that minimizes the tail probabilities of the typical distance of matched points!

Stable matching algorithm:

- Match any pair of red and blue points that are nearest to each other.
- Remove matched points, and apply same procedure repeatedly.


## The stable matching algorithm

Problem: Find a shift-invariant matching of red and blue points that minimizes the tail probabilities of the typical distance of matched points!

Stable matching algorithm:

- Match any pair of red and blue points that are nearest to each other.
- Remove matched points, and apply same procedure repeatedly.



## The stable matching algorithm

Problem: Find a shift-invariant matching of red and blue points that minimizes the tail probabilities of the typical distance of matched points!

## Stable matching algorithm:

- Match any pair of red and blue points that are nearest to each other.
- Remove matched points, and apply same procedure repeatedly.



## The stable matching algorithm

We let $F(r)$ be the expected number of red points in the box $[0,1]^{d}$ matched to a blue point at distance no more than $r$, and define a random variable $X$ denoting the typical matching length as

$$
\mathbb{P}^{*}\{X \leq r\}=F(r)
$$

## The stable matching algorithm

We let $F(r)$ be the expected number of red points in the box $[0,1]^{d}$ matched to a blue point at distance no more than $r$, and define a random variable $X$ denoting the typical matching length as

$$
\mathbb{P}^{*}\{X \leq r\}=F(r)
$$

## Holroyd, Pemantle, Peres and Schramm (2008)

If $d=1,2$ every shift-invariant matching of red and blue points satisfies

$$
\mathbb{E}^{*} X^{d / 2}=\infty
$$

The stable matching in $d=1$ has the property that

$$
\mathbb{E}^{*} X^{\alpha}<\infty \quad \text { for all } \alpha<\frac{1}{2} .
$$

## The stable matching algorithm

We let $F(r)$ be the expected number of red points in the box $[0,1]^{d}$ matched to a blue point at distance no more than $r$, and define a random variable $X$ denoting the typical matching length as

$$
\mathbb{P}^{*}\{X \leq r\}=F(r)
$$

## Holroyd, Pemantle, Peres and Schramm (2008)

If $d=1,2$ every shift-invariant matching of red and blue points satisfies

$$
\mathbb{E}^{*} X^{d / 2}=\infty
$$

The stable matching in $d=1$ has the property that

$$
\mathbb{E}^{*} X^{\alpha}<\infty \quad \text { for all } \alpha<\frac{1}{2} .
$$

How is this related to the extra head problem?

## The stable matching algorithm

In $d=1$ we modify the algorithm so that only matchings with the blue point to the left of the red point are allowed. Then a blue point is matched if its neighbour to the right is red. Matched pairs are removed and the procedure continues.

## The stable matching algorithm

In $d=1$ we modify the algorithm so that only matchings with the blue point to the left of the red point are allowed. Then a blue point is matched if its neighbour to the right is red. Matched pairs are removed and the procedure continues.


## The stable matching algorithm

In $d=1$ we modify the algorithm so that only matchings with the blue point to the left of the red point are allowed. Then a blue point is matched if its neighbour to the right is red. Matched pairs are removed and the procedure continues.


## The stable matching algorithm

In $d=1$ we modify the algorithm so that only matchings with the blue point to the left of the red point are allowed. Then a blue point is matched if its neighbour to the right is red. Matched pairs are removed and the procedure continues.


- Starting from a blue point count the number of blue and red points as you move along the line, the matching red point is the first instance when we have counted the same number of red and blue points.


## The stable matching algorithm

In $d=1$ we modify the algorithm so that only matchings with the blue point to the left of the red point are allowed. Then a blue point is matched if its neighbour to the right is red. Matched pairs are removed and the procedure continues.


- Starting from a blue point count the number of blue and red points as you move along the line, the matching red point is the first instance when we have counted the same number of red and blue points.
- The length $X$ corresponds to the first return time to the origin of the associated random walk (with exponential holding times).


## The stable matching algorithm

In $d=1$ we modify the algorithm so that only matchings with the blue point to the left of the red point are allowed. Then a blue point is matched if its neighbour to the right is red. Matched pairs are removed and the procedure continues.


- Starting from a blue point count the number of blue and red points as you move along the line, the matching red point is the first instance when we have counted the same number of red and blue points.
- The length $X$ corresponds to the first return time to the origin of the associated random walk (with exponential holding times).
- The return time satisfies $\mathbb{P}^{*}\{X>r\} \leq \mathrm{Cr}^{-\frac{1}{2}}$.


## Shifting Brownian motion

An unbiased shift of $B$ is a random time $T$, which is a function of $B$, such that $\left(B_{T+t}-B_{T}\right)_{t \in \mathbb{R}}$ is a Brownian motion independent of $B_{T}$.

Embedding problem: Given a probability measure $\nu$ find an unbiased shift $T$ such that $B_{T}$ has the distribution $\nu$.

## Shifting Brownian motion

An unbiased shift of $B$ is a random time $T$, which is a function of $B$, such that $\left(B_{T+t}-B_{T}\right)_{t \in \mathbb{R}}$ is a Brownian motion independent of $B_{T}$.

Embedding problem: Given a probability measure $\nu$ find an unbiased shift $T$ such that $B_{T}$ has the distribution $\nu$.

Tool: There exist stochastic processes ( $L_{t}^{x}: t \geq 0$ ) on the line called local times such that the value $L_{t}^{x}$ quantifies how much time $B$ has spent at level $x$ up to time $t$. In formulas

$$
\int_{0}^{t} f\left(B_{s}\right) d s=\int_{\mathbb{R}} f(x) L_{t}^{x} d x
$$

## Shifting Brownian motion

An unbiased shift of $B$ is a random time $T$, which is a function of $B$, such that $\left(B_{T+t}-B_{T}\right)_{t \in \mathbb{R}}$ is a Brownian motion independent of $B_{T}$.

Embedding problem: Given a probability measure $\nu$ find an unbiased shift $T$ such that $B_{T}$ has the distribution $\nu$.

Tool: There exist stochastic processes ( $L_{t}^{x}: t \geq 0$ ) on the line called local times such that the value $L_{t}^{x}$ quantifies how much time $B$ has spent at level $x$ up to time $t$. In formulas

$$
\int_{0}^{t} f\left(B_{s}\right) d s=\int_{\mathbb{R}} f(x) L_{t}^{x} d x
$$

Given a probability measure $\nu$ we can generalise the family of local times to a process ( $L_{t}^{\nu}: t \geq 0$ ) given by

$$
L_{t}^{\nu}=\int L_{t}^{x} d \nu(x)
$$

called the additive functional with Revuz-measure $\nu$.

## Shifting Brownian motion

## Theorem 1: Last, M and Thorisson (2012)

Suppose that $\nu$ is a probability measure with $\nu\{0\}=0$. Then

$$
T=\inf \left\{t>0: L_{t}^{0}=L_{t}^{\nu}\right\}
$$

is an unbiased shift and $B(T)$ has law $\nu$.


## Shifting Brownian motion

## Theorem 1: Last, M and Thorisson (2012)

Suppose that $\nu$ is a probability measure with $\nu\{0\}=0$. Then

$$
T=\inf \left\{t>0: L_{t}^{0}=L_{t}^{\nu}\right\}
$$

is an unbiased shift and $B(T)$ has law $\nu$.


- $T$ is also a stopping time.


## Shifting Brownian motion

## Theorem 1: Last, M and Thorisson (2012)

Suppose that $\nu$ is a probability measure with $\nu\{0\}=0$. Then

$$
T=\inf \left\{t>0: L_{t}^{0}=L_{t}^{\nu}\right\}
$$

is an unbiased shift and $B(T)$ has law $\nu$.


- The embedding property has been observed in a different context by Bertoin, Le Gall (1992).


## Shifting Brownian motion

## Theorem 1: Last, M and Thorisson (2012)

Suppose that $\nu$ is a probability measure with $\nu\{0\}=0$. Then

$$
T=\inf \left\{t>0: L_{t}^{0}=L_{t}^{\nu}\right\}
$$

is an unbiased shift and $B(T)$ has law $\nu$.


- If $\nu\{0\}>0$, say $\nu=\epsilon \delta_{0}+(1-\epsilon) \mu$ with $\mu\{0\}=0$, then $T$ is an unbiased shift embedding $\mu$.


## Shifting Brownian motion

## Theorem 2: Last, M and Thorisson (2012)

Any stopping time $T$ which is an unbiased shift embedding some $\nu$ with $\nu\{0\}=0$ satisfies

$$
\mathbb{E} T^{\frac{1}{4}}=\infty .
$$

If $\int|x| d \nu(x)<\infty$ then the $T$ constructed in Theorem 1 satisfies

$$
\mathbb{E} T^{\alpha}<\infty \quad \text { for all } \alpha<\frac{1}{4}
$$

## Shifting Brownian motion

## Theorem 2: Last, M and Thorisson (2012)

Any stopping time $T$ which is an unbiased shift embedding some $\nu$ with $\nu\{0\}=0$ satisfies

$$
\mathbb{E} T^{\frac{1}{4}}=\infty .
$$

If $\int|x| d \nu(x)<\infty$ then the $T$ constructed in Theorem 1 satisfies

$$
\mathbb{E} T^{\alpha}<\infty \quad \text { for all } \alpha<\frac{1}{4}
$$

- Our $T$ has optimal tail behaviour amongst all stopping times solving the embedding problem for unbiased shifts.


## Shifting Brownian motion

## Theorem 2: Last, M and Thorisson (2012)

Any stopping time $T$ which is an unbiased shift embedding some $\nu$ with $\nu\{0\}=0$ satisfies

$$
\mathbb{E} T^{\frac{1}{4}}=\infty .
$$

If $\int|x| d \nu(x)<\infty$ then the $T$ constructed in Theorem 1 satisfies

$$
\mathbb{E} T^{\alpha}<\infty \quad \text { for all } \alpha<\frac{1}{4}
$$

- Our $T$ has optimal tail behaviour amongst all stopping times solving the embedding problem for unbiased shifts.
- Open: Is there a better $T$ which is not a stopping time?


## Shifting Brownian motion

## Theorem 2: Last, M and Thorisson (2012)

Any stopping time $T$ which is an unbiased shift embedding some $\nu$ with $\nu\{0\}=0$ satisfies

$$
\mathbb{E} T^{\frac{1}{4}}=\infty .
$$

If $\int|x| d \nu(x)<\infty$ then the $T$ constructed in Theorem 1 satisfies

$$
\mathbb{E} T^{\alpha}<\infty \quad \text { for all } \alpha<\frac{1}{4}
$$

- Our $T$ has optimal tail behaviour amongst all stopping times solving the embedding problem for unbiased shifts.
- Open: Is there a better $T$ which is not a stopping time?
- If $\nu=\delta_{0}$ there exists unbiased shifts $T \neq 0$ with exponential moments.


## How is this related to the matching problems?

General theory of Last and Thorisson (2009) shows that
A random time $T$ is an unbiased shift embedding $\nu$.
if and only if

The mapping $\tau: \mathbb{R} \rightarrow \mathbb{R}$ given by $\tau(t)=T \circ \theta_{t}+t$ satisfies $\ell^{0} \circ \tau^{-1}=\ell^{\nu} \mathbb{P}$-almost surely.

Here $\ell^{\nu}$ is the random measure on the line with distribution function given by ( $L_{t}^{\nu}: t \in \mathbb{R}$ ), and $\mathbb{P}$ is the 'law' of stationary Brownian motion.

## How is this related to the matching problems?

General theory of Last and Thorisson (2009) shows that
A random time $T$ is an unbiased shift embedding $\nu$.
if and only if

The mapping $\tau: \mathbb{R} \rightarrow \mathbb{R}$ given by $\tau(t)=T \circ \theta_{t}+t$ satisfies $\ell^{0} \circ \tau^{-1}=\ell^{\nu} \mathbb{P}$-almost surely.

Here $\ell^{\nu}$ is the random measure on the line with distribution function given by ( $L_{t}^{\nu}: t \in \mathbb{R}$ ), and $\mathbb{P}$ is the 'law' of stationary Brownian motion.

New problem: Find a matching $\tau$ between the two random measures $\ell^{0}$ and $\ell^{\nu}$. This is a continuous version of the Poisson matching problem on the line!

## How is this related to the matching problems?

Our solution for this matching problem is also analogous to the solution of the Poisson matching and extra head problems.

## How is this related to the matching problems?

Our solution for this matching problem is also analogous to the solution of the Poisson matching and extra head problems.

- We look at the random function $f(t)=L_{t}^{0}-L_{t}^{\nu}, t \geq 0$.



## How is this related to the matching problems?

Our solution for this matching problem is also analogous to the solution of the Poisson matching and extra head problems.

- We look at the random function $f(t)=L_{t}^{0}-L_{t}^{\nu}, t \geq 0$.

- The mapping $\tau$ maps points of increase of $f$ onto points of decrease and transports the measure $\ell^{0}$ onto $\ell^{\nu}$.


## How is this related to the matching problems?

Our solution for this matching problem is also analogous to the solution of the Poisson matching and extra head problems.

- We look at the random function $f(t)=L_{t}^{0}-L_{t}^{\nu}, t \geq 0$.

- The mapping $\tau$ maps points of increase of $f$ onto points of decrease and transports the measure $\ell^{0}$ onto $\ell^{\nu}$.
Warning! This function $f$, not the Brownian motion, is the analogue of the random walk appearing in the extra head and matching problems!


## Why is the critical exponent equal to $\frac{1}{4}$ ?

## Why is the critical exponent equal to $\frac{1}{4}$ ?

The function $f$ does not behave like a random walk because it has long flat pieces, and therefore return times to zero are typically longer.

## Why is the critical exponent equal to $\frac{1}{4}$ ?

The function $f$ does not behave like a random walk because it has long flat pieces, and therefore return times to zero are typically longer.
Looking at the time-change

$$
U_{r}:=\inf \left\{t>0: L_{t}^{0}+L_{t}^{\nu}=r\right\}
$$

with respect to a clock which does not tick during the flat pieces of $f$, and defining

$$
\tilde{f}(r):=f\left(U_{r}\right), \quad \text { for all } r>0,
$$

we obtain an object which sufficiently resembles a random walk and has return times with tails of order $t^{-\frac{1}{2}}$.

## Why is the critical exponent equal to $\frac{1}{4}$ ?

The function $f$ does not behave like a random walk because it has long flat pieces, and therefore return times to zero are typically longer.
Looking at the time-change

$$
U_{r}:=\inf \left\{t>0: L_{t}^{0}+L_{t}^{\nu}=r\right\}
$$

with respect to a clock which does not tick during the flat pieces of $f$, and defining

$$
\tilde{f}(r):=f\left(U_{r}\right), \quad \text { for all } r>0,
$$

we obtain an object which sufficiently resembles a random walk and has return times with tails of order $t^{-\frac{1}{2}}$.
As $U_{r} \sim r^{2}$ by Brownian scaling, the return times for the original $f$ have tails of order $t^{-\frac{1}{4}}$.

## And why is always $\mathbb{E} T^{\frac{1}{4}}=\infty$ ?

And why is always $\mathbb{E} T^{\frac{1}{4}}=\infty$ ?
By the Barlow-Yor inequality, for all stopping times $T$,

$$
\mathbb{E}_{0}\left(L_{T}^{0}\right)^{p} \leq C \mathbb{E}_{0} T^{\frac{p}{2}} .
$$

Hence it suffices to show $\mathbb{E}_{0}\left(L_{T}^{0}\right)^{\frac{1}{2}}=\infty$.

## And why is always $\mathbb{E} T^{\frac{1}{4}}=\infty$ ?

By the Barlow-Yor inequality, for all stopping times $T$,

$$
\mathbb{E}_{0}\left(L_{T}^{0}\right)^{p} \leq C \mathbb{E}_{0} T^{\frac{p}{2}} .
$$

Hence it suffices to show $\mathbb{E}_{0}\left(L_{T}^{0}\right)^{\frac{1}{2}}=\infty$.
We look at the $\ell^{0}$ mass that is not matched within an interval

$$
\int \mathbf{1}\left\{0 \leq s \leq T_{t}, \tau(s) \notin\left[0, T_{t}\right]\right\} \ell^{0}(d s) \geq\left(L_{T_{t}}^{0}-L_{T_{t}}^{\nu}\right)_{+} .
$$

By the central limit theorem the RHS has expectation of order $\sqrt{t}$.

## And why is always $\mathbb{E} T^{\frac{1}{4}}=\infty$ ?

By the Barlow-Yor inequality, for all stopping times $T$,

$$
\mathbb{E}_{0}\left(L_{T}^{0}\right)^{p} \leq C \mathbb{E}_{0} T^{\frac{p}{2}} .
$$

Hence it suffices to show $\mathbb{E}_{0}\left(L_{T}^{0}\right)^{\frac{1}{2}}=\infty$.
We look at the $\ell^{0}$ mass that is not matched within an interval

$$
\int \mathbf{1}\left\{0 \leq s \leq T_{t}, \tau(s) \notin\left[0, T_{t}\right]\right\} \ell^{0}(d s) \geq\left(L_{T_{t}}^{0}-L_{T_{t}}^{\nu}\right)_{+} .
$$

By the central limit theorem the RHS has expectation of order $\sqrt{t}$. The expectation of the LHS is

$$
\begin{aligned}
\mathbb{E}_{0} \int_{0}^{T_{t}} 1\left\{\tau(s)-s>T_{t}-s\right\} \ell^{0}(d s) & =\int_{0}^{t} \mathbb{P}_{0}\left\{\tau\left(T_{s}\right)-T_{s}>T_{t}-T_{s}\right\} d s \\
& =\int_{0}^{t} \mathbb{P}_{0}\left\{T>T_{t-s}\right\} d s=\mathbb{E}_{0}\left[L_{T}^{0} \wedge t\right]
\end{aligned}
$$

## And why is always $\mathbb{E} T^{\frac{1}{4}}=\infty$ ?

By the Barlow-Yor inequality, for all stopping times $T$,

$$
\mathbb{E}_{0}\left(L_{T}^{0}\right)^{p} \leq C \mathbb{E}_{0} T^{\frac{p}{2}} .
$$

Hence it suffices to show $\mathbb{E}_{0}\left(L_{T}^{0}\right)^{\frac{1}{2}}=\infty$.
We look at the $\ell^{0}$ mass that is not matched within an interval

$$
\int \mathbf{1}\left\{0 \leq s \leq T_{t}, \tau(s) \notin\left[0, T_{t}\right]\right\} \ell^{0}(d s) \geq\left(L_{T_{t}}^{0}-L_{T_{t}}^{\nu}\right)_{+} .
$$

By the central limit theorem the RHS has expectation of order $\sqrt{t}$. The expectation of the LHS is

$$
\begin{aligned}
\mathbb{E}_{0} \int_{0}^{T_{t}} \mathbf{1}\left\{\tau(s)-s>T_{t}-s\right\} \ell^{0}(d s) & =\int_{0}^{t} \mathbb{P}_{0}\left\{\tau\left(T_{s}\right)-T_{s}>T_{t}-T_{s}\right\} d s \\
& =\int_{0}^{t} \mathbb{P}_{0}\left\{T>T_{t-s}\right\} d s=\mathbb{E}_{0}\left[L_{T}^{0} \wedge t\right]
\end{aligned}
$$

If $\mathbb{E}_{0}\left(L_{T}^{0}\right)^{\frac{1}{2}}<\infty$ the RHS would be of strictly smaller order than $t^{\frac{1}{2}}$, contradicting the central limit theorem.

