

Def. 8 Let  $\sigma: V \rightarrow V$  be a permutation. Define the permutation matrix  $P^\sigma \in \mathbb{R}^{V \times V}$  by

$$P_{i,j}^\sigma = \begin{cases} 1, & \text{if } i = \sigma(j), \\ 0, & \text{otherwise.} \end{cases}$$

Let  $X \in S^V$  be a symmetric matrix. Define the left action of  $\sigma$  on  $X$  by

$$\sigma(X) = P^\sigma X (P^\sigma)^T = (X_{\sigma^{-1}(i), \sigma^{-1}(j)})_{i,j \in V}.$$

Lemma 9 Let  $G = (V, E)$  be a graph. Consider

$$\begin{aligned} \mathcal{D}(G) &= \max \langle J, X \rangle \\ &X \in S_{\geq 0}^V, \text{Tr}(X) = 1, \\ &X_{ij} = 0 \text{ if } \{i, j\} \notin E. \end{aligned}$$

This optimisation problem has an optimal solution  $X^*$  which is invariant under  $\text{Aut}(G)$ , i.e.  $\sigma(X^*) = X^*$  for all  $\sigma \in \text{Aut}(G)$ .

Proof Let  $X$  be an optimal solution of  $\mathcal{D}(G)$ ; which exists by strong duality. Then  $\sigma(X)$  is also an optimal solution of  $\mathcal{D}(G)$ . (check it!).

Define  $X^* = \frac{1}{|\text{Aut}(G)|} \sum_{\sigma \in \text{Aut}(G)} \sigma(X)$ , which again is an optimal solution of  $\mathcal{J}(G)$ . By construction, we have  $\sigma(X^*) = X^*$  for all  $\sigma \in \text{Aut}(G)$  because

$$\begin{aligned} \sigma(X^*) &= \frac{1}{|\text{Aut}(G)|} \sum_{\tau \in \text{Aut}(G)} \sigma \tau(X) \\ &= \frac{1}{|\text{Aut}(G)|} \sum_{\tau \in \text{Aut}(G)} \tau(X) = X^*. \end{aligned}$$

□

Proposition 10 Let  $G = (V, E)$  be a vertex transitive graph.

Then there is an optimal solution  $X^*$  of  $\mathcal{J}(G)$  with

$$X_{ii}^* = \frac{1}{|V|} \text{ for all } i \in V, \text{ and}$$

$$X_{e}^* = \frac{\mathcal{J}(G)}{|V|} e.$$

Proof Let  $X^*$  be an optimal solution of  $\mathcal{J}(G)$  which is invariant under  $\text{Aut}(G)$  (see ~~prop.~~ Lemma 9). By Ex. 12.2

$$X^* e = \mathcal{J}(G) \text{diag } X^*$$

So we have to show that  $\text{diag } X^* = \left( \frac{1}{|V|}, \dots, \frac{1}{|V|} \right)$ .

Since  $G$  is vertex transitive we have for  $i, j \in V$

$$X_{ij}^* = X_{\sigma^{-1}(i), \sigma^{-1}(j)}^* = \sigma(X^*)_{ii} = X_{ii}^*$$

for some  $\sigma \in \text{Aut}(G)$  with  $\sigma(j) = i$ . Hence all diagonal coefficients of  $X^*$  coincide. Since  $\text{Tr}(X^*) = 1$ , we have  $X_{ii}^* = \frac{1}{|V|}$ .  $\square$

Theorem 11 If  $G = (V, E)$  is vertex transitive, then

$$\mathcal{J}(G) \mathcal{J}(\bar{G}) = |V|.$$

Proof  $\mathcal{J}(G) \mathcal{J}(\bar{G}) \geq |V|$ :

Consider dual SDP

$$\begin{aligned} \mathcal{J}(G) = \min t \\ z - j \geq 0, \quad z_{ii} = t, \quad i \in V \\ z_{ij} = 0 \quad \text{if } \{i, j\} \notin E(G) \end{aligned}$$

Let  $X$  be optimal for  $\mathcal{J}(G)$ ,  $\bar{X}$  be optimal for  $\mathcal{J}(\bar{G})$ .

We have

$$0 \leq \langle X - j, j \rangle = \langle X, j \rangle - \underbrace{\langle j, j \rangle}_{|V|^2} \Rightarrow \langle X, j \rangle \geq |V|^2.$$

Similarly,  $\langle \bar{X}, j \rangle \geq |V|^2$ .

Furthermore,

$$\begin{aligned}\langle X, \bar{X} \rangle &= \sum_{i,j \in V} X_{ij} \bar{X}_{ij} = \sum_{i \in V} X_{ii} \bar{X}_{ii} \\ &= |V| \mathcal{J}(G) \mathcal{J}(\bar{G}).\end{aligned}$$

We also have

$$0 \leq \langle X - J, \bar{X} \rangle = \langle X, \bar{X} \rangle - \langle X, J \rangle \leq \langle X, \bar{X} \rangle - |V|^2.$$

So

$$|V|^2 \leq \langle X, \bar{X} \rangle = |V| \mathcal{J}(G) \mathcal{J}(\bar{G}) \Rightarrow |V| \leq \mathcal{J}(G) \mathcal{J}(\bar{G}).$$

[This inequality is valid for arbitrary graphs  $G$ ].

$$\underline{\mathcal{J}(G) \mathcal{J}(\bar{G}) \leq |V| :}$$

Let  $X^*$  be an optimal solution of the primal SDP  $\mathcal{J}(G)$  as in Proposition 10. Define a feasible solution  $Y$  of the dual SDP  $\mathcal{J}(\bar{G})$  as follows:  $Y = \frac{|V|^2}{\mathcal{J}(G)} X^*$ , then

$$t = \frac{|V|}{\mathcal{J}(G)}. \quad (\Rightarrow \mathcal{J}(G) \mathcal{J}(\bar{G}) \leq \mathcal{J}(G) \frac{|V|}{\mathcal{J}(G)} = |V|).$$

$Y$  is indeed feasible because:

$$Y_{ij} = 0 \quad \text{for } \{i, j\} \in E(G) : \checkmark$$

$$Y - J \geq 0 :$$

$$\frac{|V|^2}{J(G)} X^* - J \geq 0 \text{ because}$$

$$\frac{|V|^2}{J(G)} X^* e - J e = \frac{|V|^2}{J(G)} \frac{J(G)}{|V|} e - |V| e = 0.$$

(eigenvectors of  $J$  are  $\text{Re}\{z\}$  and  $(\text{Re})^\perp\{z\}$ ).

□

Corollary 12  $J(C_n) J(\bar{C}_n) = n.$

$$\Rightarrow J(C_5) = \sqrt{5}.$$