Point Process Models Quantitative Risk Management

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Point Process Models

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• Exceedances of thresholds as events in time

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- Point process to model the occurrence of these events
- POT model as a starting point for developing more dynamic descriptions
- POT model subsumes the models for maxima and the GPD models

Threshold exceedances for strict white noise

- Strict white noise process $(X_i)_{i\in\mathbb{N}}$ representing financial losses
 - iid
 - $\mathbb{E}[X] = 0$
 - $\sigma^2 = \mathbb{E}[X^2] < \infty$

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Threshold exceedances for strict white noise

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 - $\mathbb{E}[X] = 0$
 - $\sigma^2 = \mathbb{E}[X^2] < \infty$
- Common loss distribution \in MDA(H_{ξ}), that means

$$\lim_{n\to\infty}F(c_nx+d_n)=H_{\xi}(x))$$

$$\Rightarrow \lim_{n\to\infty} n\ln(F(c_nx+d_n)) = \ln(\lim_{n\to\infty}(F^n(c_nx+d_n))) = \ln(H_{\xi}(x)).$$

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Assumptions

Threshold exceedances for strict white noise

• Sequence of thresholds $(u_n(x))$ defined by $u_n(x) := c_n x + d_n$, so that

$$\lim_{n\to\infty} n\ln(F(c_nx+d_n)) = \lim_{n\to\infty} n\ln(F(u_n(x))) = \ln(H_{\xi}(x))$$

and with $\lim_{y\to 1} -ln(y) = 1 - y$ it follows

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• $N_{u_n(x)} := \#\{i \in \{1, ..., n\} : X_i > u_n\}$ is the number of exceedances of $u_n(x)$ by $X_1, ..., X_n$ with $N_{u_n(x)} \sim B(n, \overline{F}(u_n(x)))$. $N_{u_n(x)}$ converges to a Poisson RV with mean $\lambda(x) = -ln(H_{\xi}(x))$ as $n \to \infty$.

Poisson Point Processes

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Definition

Let $X_1, ..., X_n$ be a sequence of RV's on some state space \mathcal{X} . The point process $N(\cdot)$, defined as $N_n(A) = \sum_{i=1}^n \mathbb{1}_{\{X_n \in A\}}$ for any set $A \subset \mathcal{X}$, is called a Poisson point process (or Poisson random measure) with intensity measure Λ if the following two conditions are satisfied

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(a) For $A \subset \mathcal{X}$ and $k \geq 0$,

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(b) For any m ≥ 1, if A₁, ..., A_m are mutually disjoint subsets of X, then the RVs N(A₁), ..., N(A_m) are independent.

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Intensity measure and intensity function

The Intensity or mean measure $\Lambda(\cdot)$ has the following properties:

- $\Lambda(A) = \mathbb{E}[N(A)]$ for $A \subset \mathcal{X}$,
- $\Lambda(A) = \int_A \lambda(x) dx$, where $\lambda(x)$ is the intensity function or rate and $A \subset \mathcal{X}$.

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- $Y_{i,n} = (i/n) \mathbb{1}_{\{X_i > u_n(x)\}}$ for $n \in \mathbb{N}$ and $1 \le i \le n$ is either the normalized "time" i/n of an exceedance or zero

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- N_n(A) = ∑ⁿ_{i=1} 𝔅 {Y_{i,n∈A}} is the point process of exceedances of the threshold u_n with state space X = (0, 1].

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Hence we can say

 $N_n(\cdot)$ converges in distribution on \mathcal{X} to a Poisson point process $N(\cdot)$

$$\lim_{n\to\infty}\mathbb{P}[N_n(A)\leq k]=\mathbb{P}[N(A)\leq k], k\in\mathbb{N}.$$

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The Poisson point process $N(\cdot)$ has intensity measure $\Lambda(\cdot)$ satisfying $\Lambda(A) = (t_2 - t_1)\lambda(x)$ for $A = (t_1, t_2) \subset \mathcal{X}$, where $\lambda(x) = \lambda = -\ln(H_{\xi})$

$$\Rightarrow \mathbb{E}[N_n(A)] \rightarrow \mathbb{E}[N(A)] = \Lambda(A) = (t_2 - t_1)\lambda(x)$$

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We call this limiting process a *homogeneous Poisson process* with intensity λ .

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 λ = −*ln*(*H*_ξ(*y*)) = −*ln*(*H*_ξ((*u* − *d_n*)/*c_n*)).

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- the number of threshold exceedances of u can be approximated by a Poisson RV,
- the point process of exceedances of *u* can be approximated by a homogeneous Poisson process with rate

$$\lambda = -\ln(H_{\xi}(y)) = -\ln(H_{\xi}((u-d_n)/c_n)).$$

Replace c_n and d_n by $\sigma > 0$ and μ to get a Poisson process with rate $-ln(H_{\xi,\mu,\sigma}(u))$.

 \Rightarrow Exceedances of the level $x \ge u$ occur according to a Poisson process with rate $-ln(H_{\xi,\mu,\sigma}(x))$. That shows us the relation between the GEV model for block maxima and this model.

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 - (c) excess amounts are generalized Pareto distributed.
- Sometimes it is called marked Poisson point process where
 - (i) Exceedance times constitute the points and
 - (ii) GPD-distributed excesses are the marks.

The POT model can also be described as a (non-homogeneous) *two-dimensional Poisson* point process with points (t,x) with t time and x magnitude of exceedances. Assume:

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- $X_1, ..., X_n$ are regularly spaced random losses,
- *u* is a high threshold,
- $\mathcal{X}=(0,1] imes(u,\infty)$,
- the point process defined by $N(A) = \sum_{i=1}^{n} \mathbb{1}_{\{(i/n,X_i) \in A\}}$ is a Poisson process with intensity at a point(t, x) given by

$$\lambda(x) = \begin{cases} \frac{1}{\sigma} \left(1 + \xi \frac{x-\mu}{\sigma} \right)^{-1/\xi - 1} &, (1 - \xi(x-\mu)/\sigma) > 0\\ 0 &, otherwise. \end{cases}$$
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For a set of the form $A=(t_1,t_2) imes (x,\infty)\subset \mathcal{X}$, the intensity measure is

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⇒ For any $x \ge u$, the implied one-dimensional process of exceedances of the level x is a homogeneous Poisson process with rate $\tau(x) := -ln(H_{\xi,\mu,\sigma}(x)).$

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For a set of the form $A=(t_1,t_2) imes (x,\infty)\subset \mathcal{X}$, the intensity measure is

$$\Lambda(A) = \int_{t_1}^{t_2} \int_x^{\infty} \lambda(y) \mathrm{d}y \mathrm{d}t = -(t_2 - t_1) \ln(H_{\xi,\mu,\sigma}(x)).$$

⇒ For any $x \ge u$, the implied one-dimensional process of exceedances of the level x is a homogeneous Poisson process with rate $\tau(x) := -\ln(H_{\xi,\mu,\sigma}(x))$. The tail of the excess of $\bar{F}_u(x)$ can be calculated as the ratio of the rates of exceeding the levels u + x and u. We obtain

$$\bar{F}_u(x) = \frac{\tau(u+x)}{\tau(u)} = \left(1 + \frac{\xi x}{\sigma + \xi(u-\mu)}\right)^{-1/\xi} = \bar{G}_{\xi,\beta}(x)$$

for a positive scaling parameter $\beta = \sigma + \xi(u - \mu)$.

Relation to the GEP and GEV models

• $\bar{G}_{\xi,\beta}$ is precisely the tail of the GPD model for excesses over the threshold u with the parameter β .

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- $\bar{G}_{\xi,\beta}$ is precisely the tail of the GPD model for excesses over the threshold u with the parameter β .
- The relation to the GEV model is shown through the following: Assume we have an event {M_n ≤ x} for some value x ≥ u. In point process language that is an event that there are no points in the set A = (0,1] × (x,∞).

$$\Rightarrow \mathbb{P}[M_n \leq x] = \mathbb{P}[N(A) = 0] = e^{-\Lambda(A)} = H_{\xi,\mu,\sigma}(x) \geq u.$$

This is precisely the GEV model for maxima of n-blocks.

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Advantage

• the parameters ξ, μ and σ do not have any dependence on the threshold chosen unlike the parameter β in the GPD model

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- the estimated parameters of the Poisson model are roughly stable over a range of high thresholds
- \Rightarrow The intensity (1) is often used as a framework to introduce covariate effects into extreme value modeling

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For exceedance data $\{ ilde{X}_j: j=1,...,N_u\}$ the likelihood is

$$L(\xi,\sigma,\mu:\tilde{X}_1,...,\tilde{X}_{N_u})=e^{-\tau(u)}\prod_{j=1}^{N_u}\lambda(\tilde{X}_j).$$

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The intensity in (1) can therefore be written as

$$\lambda(x) = \lambda(t, x) = \frac{\tau}{\beta} \left(1 + \xi \frac{x - u}{\beta}\right)^{-1/\xi - 1},$$

with $\xi \in \mathbb{R}$ and $\tau,\beta >$ 0, where

$$au= au(u)=-\mathit{ln}(\mathit{H}_{\xi,\mu,\sigma}(u)) ext{ and } eta=\sigma+\xi(u-\mu)$$

The log-likelihood for the parameters ξ,σ,μ can be written as

$$ln(L(\xi,\sigma,\mu;\tilde{X}_1,...,\tilde{X}_{N_u})) = lnL_1(\xi,\beta;\tilde{X}_1-u,...,\tilde{X}_{N_u}-u) + lnL_2(\tau;N_u).$$

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- L1: likelihood for fitting a GPD to excess losses,
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This is easier to calculate and shows the relation to the GPD and GEV model because

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First calculate ξ and β in a GPD-analysis and then τ by its MLE N_u to get the estimates of μ and σ .

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Consider the POT model with financial return data where returns are discrete-time measurements.

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Solution

- \rightarrow Decluster financial return data:
 - Identify clusters by using the runs method for example.
 - Identify the maximum excess in each cluster.
 - Apply the POT model to these maxima only.

Applicability

General application on declustered data

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Although we can use the POT on declustered data to say something about

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 derive a GPD model for excess losses over thresholds for cluster maxima

but by neglecting the modeling of cluster formation we however cannot make more dynamic statements about the intensity of occurrance of threshold exceedances at any point in time.



Figure: (a)Time series of AT&T weekly percentage losses from 1991 to 2000. (b)Corresponding realization of the marked point process of exceedances of the threshold 2.75%. (c)Q-Q plot of inter-exceedance times against an exponential reference distribution.

We use weekly return data which include 102 weekly percentage losses for the AT&T stock price exceeding a threshold of 2.75%.

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- $\hat{\xi} = 0.22$,
- $\hat{\mu} = 19.9$,
- $\hat{\sigma} = 5.95$,
- and the estimated exceedance rate

$$\hat{\tau}(2.75) = -\ln(H_{\hat{\xi},\hat{\mu},\hat{\sigma}}(2.75)) = 102.$$

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We can also calculate for example $\hat{\tau}(15) = 2.50$ and get that losses exceeding 15% occur as a Poisson process with rate 2.5 per ten-year period.

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Thank you for your attention!

Elisa Jurgschat

Point Process Models

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Literature

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