

Spaces of algebraic measure trees and triangulations of the circle

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ESSEN

Offen im Denken

From graph-theoretic trees to \mathbb{R} -trees

- Graph-theoretic trees have many applications from computer science to theoretical biology.
 - \rightsquigarrow **How to define limit objects** as the size of trees tend to infinity?
- Local structure approaches yield countably infinite graphs.
 - \rightsquigarrow Benjamini-Schramm approach: [BENJAMINI & SCHRAMM (2001)], [ALDOUS & LYONS (2007)]
- We here seek a *global structure approach*: metric spaces with rescaled distances lead to \mathbb{R} -trees: [TITS (1977)]
 - study of isometry groups of hyperbolic spaces [MORGAN & SHALEN (1982)],
 - study of the fundamental groups of one-dimensional spaces [MAYER, NIKIEL & OVERSTEEGEN (1992)]
 - characterization of the topological structure of one-dimensional spaces [FISHER & ZASTROV (2013)], [FABEL (2015)]

Our motivation in \mathbb{R} -trees

- ↪ suitable **state space for tree-valued stochastic processes** that are continuum analogues of ...
- the *Aldous-Broder algorithm* for sampling a uniform spanning tree
 - of the complete graph ([EVANS, PITMAN & W. (2006)]) or
 - the high-dimensional torus [ANGTUNCIO-HERNANDEZ, BERZUNZA-OJEDA & W. (IN PROGRESS)]])
 - *subtree prune and regraft* algorithm used in reconstructing phylogenetic trees [EVANS & W. (2006)]
 - *evolving genealogies* in population genetics [(GREVEN, PFAFFELHUBER & W. (2013)), [GREVEN, SUN & W. (2016)]]
 - *pruning* procedures [ABRAHAM, DELMAS & VOISIN (2010)], [LÖHR, VOISIN & W. (2013)], [HE & WINKEL (2019)], [BERZUNZA & W. (2023)]
- ↪ all these encode trees as \mathbb{R} -trees and equip the tree space with Gromov-Hausdorff or Gromov-weak topology

We want to shift focus from metric to tree structure

↪ useful for several reasons

- 1 *The state space* of metric (measure) trees *is not compact*.
 - Tightness for random metric (measure spaces) are often not easy to check, or
 - some natural sequences of trees do not even converge as rescaled metric measure spaces, e.g. binary search tree
- 2 *The metric structure is often less canonical than the tree structure*, e.g. in situations where edge lengths are not of the same order.
- 3 Certain *functionals* of the tree structure might *not* be *continuous*.
 - ↪ For example, the degree of a vertex.

From topological structure to tree structure

- ~> ignore metric and focus on “tree-structure”
 - Unlike for metric spaces, for general topological spaces no useful notion of convergence is known.
 - For *tree spaces*, we can rely on the notion of a *branch point map* that sends any three points to a branch point.
 - ~> algebraic trees
 - We can also use the branch point map to define convergence of algebraic (measure) trees.

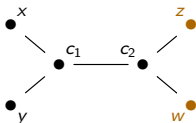
What are continuum trees? \mathbb{R} -trees

Definition ([TITS (1977)], [DRESS (1994)], [CHISWELL (2001)])

A metric space (T, d) is an **\mathbb{R} -tree** iff

- (T, d) is *connected*.
- (T, d) is *0-hyperbolic*, i.e., $\forall x_1, x_2, x_3, x_4 \in T$,

$$d(x_1, x_2) + d(x_3, x_4) \leq \max \{ d(x_1, x_3) + d(x_2, x_4), d(x_1, x_4) + d(x_2, x_3) \}.$$



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\rightsquigarrow **Intrinsic property**

For $x_1, x_2, x_3 \in T$ there exists a *unique branch point* $c(x_1, x_2, x_3) \in T$ with

$$[x_1, x_2] \cap [x_2, x_3] \cap [x_2, x_3] = \{c(x_1, x_2, x_3)\}.$$

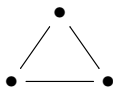
Note that

$$[x, y] := \{x' \in T : d(x, y) = d(x, x') + d(x', y)\}$$

does not require the notion of *connectedness*.

What are limit trees? metric trees

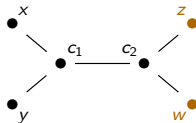
↪ *drop connectedness*



I am not a tree :-)



I am a tree :-)



Definition ([ATHREYA, LÖHR, W. (2016)])

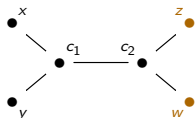
A metric space (T, d) is a *metric tree* if it is (isometric to) a subset of an \mathbb{R} -tree with $c(x, y, z) \in T$ for all $x, y, z \in T$.

In both cases we can conclude

- Symmetry of $c(x, y, z)$ in x, y, z .
- (2-point condition) $c(x, y, y) = y$, and
- (3-point condition) $c(x, y, c(x, y, z)) = c(x, y, z)$
- (4-point condition) $c(x, y, z) \in \{c(x, y, w), c(x, z, w), c(y, z, w)\}$.

Algebraic measure trees

characterize trees by map that sends three vertices to their branch point



Definition (algebraic trees; [LÖHR, W.])

(T, c) is an **algebraic tree** with **branch point map** $c = c_T: T^3 \rightarrow T$ if

- c is *symmetric*: $c(x, y, z) = c(y, x, z) = c(x, z, y)$, for all $x, y, z \in T$.
- *2-point condition*: $c(x, y, y) = y$, $x, y \in T$.
- *3-point condition*: $c(x, y, c(x, y, z)) = c(x, y, z)$, for all $x, y, z \in T$.
- *4-point condition*: For all $x, y, z, w \in T$.

$$c(x, y, z) \in \{c(x, y, w), c(x, z, w), c(y, z, w)\}.$$

↪ Finite algebraic trees correspond to finite graph-theoretic trees.

Axioms are sufficient to capture the tree-structure

Let (T, c) be an algebraic tree.

- The *path* between $x_1, x_2 \in T$ is given by

$$[x_1, x_2] := \{z \in T : z = c(x_1, x_2, z)\}.$$

Then for all $x, y, z \in T$,

$$[x, y] \cap [x, z] \cap [y, z] = \{c(x, y, z)\}.$$

- $\{x_1, x_2\}$ is an *edge* if $[x_1, x_2] := \{x_1, x_2\}$.
- $A \subseteq T$ is a *subtree* if $c(A^3) \subseteq A$.
- Similarly, we can define *branch points*, *leaves*, ...

Morphisms of algebraic trees

↪ Like any decent algebraic structure, algebraic trees come with the notion of a structure-preserving morphism.

Let (T, c) and (T', c') be algebraic trees.

- 1 A map $f : T \rightarrow T'$ is called a *tree homomorphism*, if for all $x, y, z \in T$, $f(c(x, y, z)) = c'(f(x), f(y), f(z))$.
- 2 Equivalently, for all $x, y \in T$, $f([x, y]) \subseteq [f(x), f(y)]$.

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If a homomorphism $f : T \rightarrow T'$ is bijective, we refer to it as *isomorphism*.

Algebraic trees as topological spaces

Let (T, c) be an algebraic tree.

↪ What is a good *notion of open sets*?

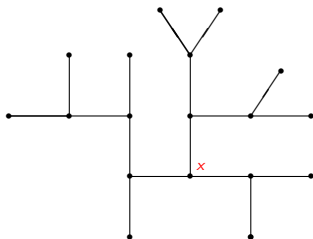
- Taking away $x \in T$, T decomposes into *subtree components*.

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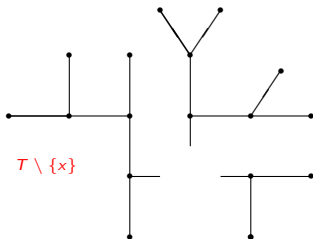


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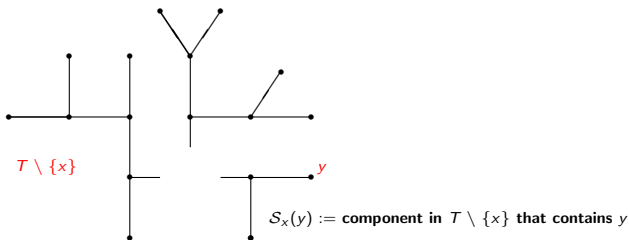


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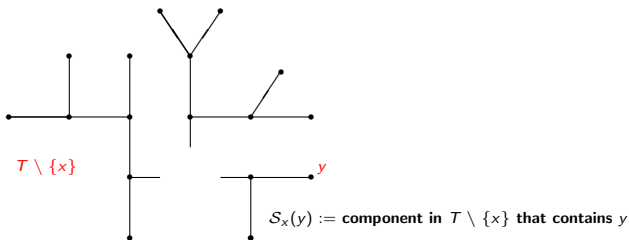


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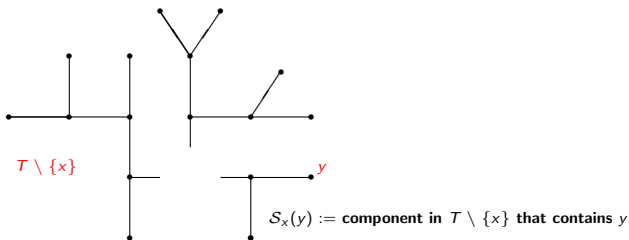
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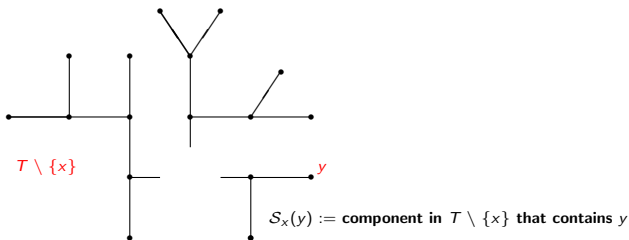
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- This *component topology* is a Hausdorff topology.

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- $\tau := \tau(\{S_x(y); x \neq y \in T\})$.
- This *component topology* is a Hausdorff topology.
- The branch point map is continuous with respect to the component topology.

↷ *Intervals are closed sets.*

Indeed, with $\mathcal{S}_u(v)$ subtree component of $T \setminus \{u\}$ that contains v

$$\mathbb{C}[x, y] = \{\mathcal{S}_u(v) : u \in [x, y], v \in T, \mathcal{S}_u(v) \cap [x, y] = \emptyset\} \in \tau(C).$$

Proposition (Löhr & W. (2021))

Let (T, c) be an algebraic tree. Then the following are equivalent:

1. The topological space (T, τ) is separable, and has only countably many edges.
2. There exists a countable set D such that for all $x, y \in T$ with $x \neq y$,

$$D \cap [x, y] \neq \emptyset.$$

In what follows, we refer to (T, c) as **(order) separable** iff the topological space (T, c) is separable and (T, c) has at most countably many edges.

Metric representation of order separable algebraic trees

- Any separable metric tree (T, r) defines an order separable algebraic tree $(T, c_{(T,r)})$ by letting $c_{(T,r)}$ send any triple $x, y, z \in T$ to its branch point in (T, r) .
- On the contrary, if (T, c) is an order separable algebraic tree and ν is a measure on $\mathcal{B}(T, c)$, then

$$r_\nu(x, y) := \nu([x, y]) - \frac{1}{2}\nu(\{x\}) - \frac{1}{2}\nu(\{y\}), \quad x, y \in T$$

defines a *pseudo-metric* with $c = c_{(T, r_\nu)}$.

- r_ν is a metric, if $\nu([x, y]) > 0$ for all $x, y \in T$.

Such a measure always exists if (T, c) is order separable. Take e.g. a probability measure supported on a countable set D such that for all $x, y \in T$,

$$D \cap [x, y] \neq \emptyset.$$

Definition

An **algebraic measure tree** (T, c, μ) consists of an *(order) separable* algebraic tree (T, c) and a *probability measure* μ on $(T, \mathcal{B}(T, c))$.

Call two algebraic measure trees (T, c, μ) and (T', c', μ') **equivalent** iff $\text{supp}(\mu)$ and $\text{supp}(\mu')$ are subtrees, and there is an *isomorphism* $\varphi : \text{supp}(\mu) \rightarrow \text{supp}(\mu')$ such that

- for all $x, y, z \in T$, $\varphi(c(x, y, z)) = c(\varphi(x), \varphi(y), \varphi(z))$, and
- $\mu \circ \varphi^{-1} = \mu'$.

$\mathbb{T} :=$ space of all equivalence classes of algebraic measure trees.

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\rightsquigarrow Related approaches to continuum trees:

- **didendritic systems**; [EVANS, GRÜBEL & WAKOLBINGER (2017)]
- **interval partition trees**; **exchangeable hierarchies** [FORMAN (2020)]

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\rightsquigarrow **Three strategies** for a notion of convergence in \mathbb{T} .

- 1 rely on Gromov-weak topology
- 2 use combinatorial notion of convergence
- 3 rely on convergence of subtree component masses

Convergence of metric measure spaces

- *mm-space* (X, d, μ) = a Polish space (X, d) + a probability measure μ on $\mathcal{B}(X)$

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$\mathbb{H} :=$ equivalence classes of mm-trees.

- We evaluate elements in \mathbb{H} with *sample distance polynomials*, i.e.,

$$\Phi^{m,\phi}(T, d, \mu) := \int \mu^{\otimes m}(d\underline{x}) \phi\left(\left(d(x_i, x_j)\right)_{1 \leq i < j \leq m}\right)$$

where $m \in \mathbb{N}$, $\phi \in \mathcal{C}_b(\mathbb{R}_+^{\binom{m}{2}})$.

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where $m \in \mathbb{N}$, $\phi \in C_b(\mathbb{R}_+^{\binom{m}{2}})$.

- (*Vershik's reconstruction theorem*) If $x_1, x_2 \in \mathbb{H}$ such that $\Phi(x_1) = \Phi(x_2)$ for all sample distance polynomial then $x_1 = x_2$.

[GREVEN, PFAFFELHUBER & W. (2009)]

Definition (Gromov-weak topology)

A sequence $(x_n)_{n \in \mathbb{N}}$ converges *Gromov-weakly* to x in \mathbb{H} iff

$$\Phi(x_n) \longrightarrow \Phi(x) \quad \text{for all sample distance polynomials } \Phi.$$

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[LÖHR (2013)]

Corollary (Convergence determining)

If $(x_N)_{N \in \mathbb{N}}$ and x are \mathbb{H} -valued *random variables* with

$$\mathbb{E}[\Phi(x_N)] \xrightarrow{N \rightarrow \infty} \mathbb{E}[\Phi(x)]$$

for all sample distance polynomials. Then

$$\mathcal{L}(x_N) \xrightarrow{N \rightarrow \infty} \mathcal{L}(x).$$

The branch point distribution distance

↪ for an order separable tree (T, c) there are many metric representations

Question. Is there an intrinsic choice?

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Question. Is there an intrinsic choice?

Definition (Branch point distribution distance)

Let (T, c, μ) be an algebraic measure tree. The probability measure

$$\nu_{(T, c, \mu)} := \mu^{\otimes 3} \circ c^{-1}$$

is called the *branch point distribution*. and the associated metric r_ν the *branch point distribution distance*.

We say that a sequence $(x_N)_\mathbb{N}$ converges *globally* to x in \mathbb{T} , if $(x_N)_\mathbb{N}$ converges *Gromov-weakly* to x in \mathbb{T} with respect to the branch point distribution distance.

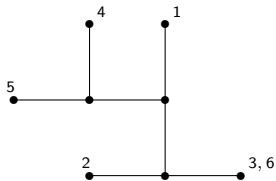
A combinatorial notion of convergence

↪ In many applications trees are binary.

$\mathbb{T}_2 := \{ \text{binary algebraic measure trees with } \textit{atoms only at leaves} \}$

An *m-cladogram* is a combinatorial

- un-rooted, binary tree
- leaf-labeled, i.e., there is a surjective *labeling map* $\ell : \{1 \dots m\}$ to the set of leaves.



Two *m-cladograms* (C_1, c_1, ℓ_1) and (C_2, c_2, ℓ_2) are **equivalent** if they are *label invariant isomorphic*.

Sample shape

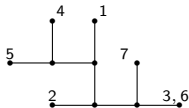
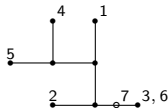
↪ encode the shape of a sampled subtree as *cladogram*

Definition (tree shape)

Fix $(T, c_T) \in \mathbb{T}_2$, $m \in \mathbb{N}$, and non-branch points $u_1, \dots, u_m \in T$. The **tree shape** $\mathfrak{s}_T(u_1, \dots, u_m)$ is the unique (up to isomorphism) m -cladogram with

- (sh1) leaf set $\{u_1, \dots, u_m\}$,
- (sh2) u_i gets label i for all $i = 1, \dots, m$, and such that
- (sh3) the identity on the leaf set extends to a tree homomorphism from $\mathfrak{s}_T(u_1, \dots, u_m)$ onto $c_T(\{u_1, \dots, u_m\}^3)$.

↪ (sh3) tells us what to do when there are 3 points on a path.



Sample shape distribution

Consider *sample shape polynomials*, i.e. functions $\Phi : \mathbb{T}_2 \rightarrow \mathbb{R}$ of the form

$$\Phi(\mathcal{X}) = \int \mu^{\otimes m}(\mathrm{d}\underline{x}) \phi(\mathfrak{s}_T(\underline{x}))$$

for some $m \in \mathbb{N}$ and $\phi : \mathcal{C}_m \rightarrow \mathbb{R}_+$.

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Proposition (Löhr & W. (2021))

For each $m \in \mathbb{N}$ and $\varphi \in \mathcal{C}(\mathbb{R}^{\binom{m}{2}})$, the *sample distance polynomial*

$$\Phi(x) = \int \mu^{\otimes m}(d\underline{x}) \phi((r_\nu(x_i, x_j))_{1 \leq i < j \leq m})$$

can be approximated uniformly by *sample shape polynomials*.

Sample shape distribution

Main steps in proof:

- 1 Recall that $\nu = c_*\mu^{\otimes 3}$ and

$$r_\nu(x, y) = \nu([x, y]) - \frac{1}{2}\nu(\{x\}) - \frac{1}{2}\nu(\{y\}).$$

- 2 Approximate ν by *empirical branch point distributions*,

$$\nu_{n, \underline{u}} := \frac{1}{n} \sum_{i=0}^{n-1} \delta_{c(u_{3i+1}, u_{3i+2}, u_{3i+3})},$$

and note that $\Phi(x) := \int \mu^{\otimes 3m}(\underline{d}\underline{u}) \phi((r_{\nu_{n, \underline{u}}}(u_i, u_j))_{1 \leq i < j \leq 3m})$ is a sample shape polynomial because whether or not $u_i \in [u_k, u_l]$ depends on $s_T(\underline{u})$.

- 3 Use the uniform upper bound ([VAPNIK & CHERVONENKIS (1971)])

$$\mathbb{E} \left[\sup_{x, y \in T} |\nu([x, y]) - \nu_{n, \underline{u}}([x, y])| \right] \leq 96 \sqrt{\frac{\dim_{VC}(\{[x, y]; x, y \in T\})}{n}},$$

and note that $\dim_{VC}(\{[x, y]; x, y \in T\}) = 2$.

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Sample shape convergence

Distance polynomials can be approximated uniformly by *shape polynomials*.

Consequently, if $x, x' \in \mathbb{T}_2$ then

$$x = x' \text{ iff } \Phi^{m,\phi}(x) = \Phi^{m,\phi}(x'), \forall m \in \mathbb{N}, \phi : \mathfrak{C}_m \rightarrow \mathbb{R}.$$

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Definition (Sample shape convergence)

We say that a sequence $(x_n)_{n \in \mathbb{N}}$ converges in *sample shape* to x in \mathbb{T}_2 if all sample shape polynomials converge.

Sample shape convergence

Distance polynomials can be approximated uniformly by *shape polynomials*.

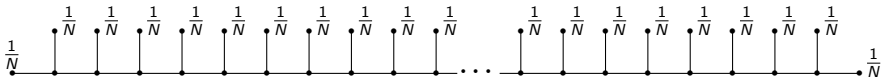
Consequently, if $x, x' \in \mathbb{T}_2$ then

$$x = x' \text{ iff } \Phi^{m,\phi}(x) = \Phi^{m,\phi}(x'), \forall m \in \mathbb{N}, \phi : \mathfrak{C}_m \rightarrow \mathbb{R}.$$

Definition (Sample shape convergence)

We say that a sequence $(x_n)_{n \in \mathbb{N}}$ converges in *sample shape* to x in \mathbb{T}_2 if all sample shape polynomials converge.

↪ For example, the *comb tree* with N leaves and uniform distribution on the leaves *converges in sample shape to a line segment* with a continuous mass distribution.



Sample subtree mass convergence

↪ yet another notion of convergence -:)

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given $(T, c, \mu) \in \mathbb{T}_2$, pick U_1, U_2, \dots i.i.d. $\sim \mu$

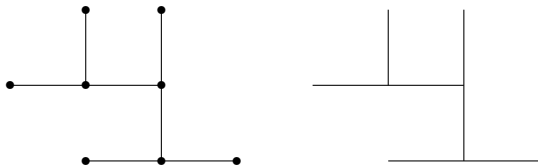
- Consider the subtree $S_{(T,c)}(U_1, \dots, U_m)$, and label the generated branch points according to the order of their appearance.
- Evaluate the masses of the subtrees branching off.

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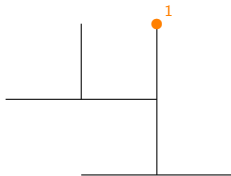
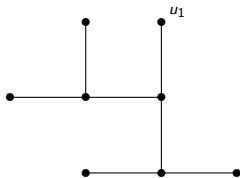


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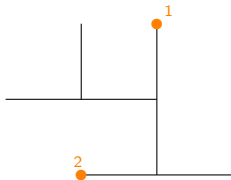
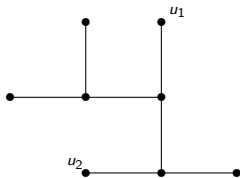


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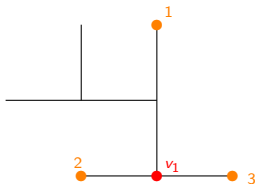
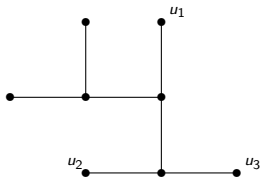


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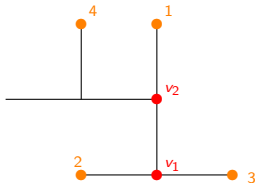
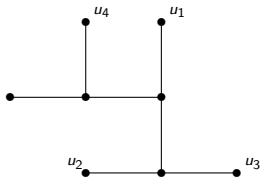


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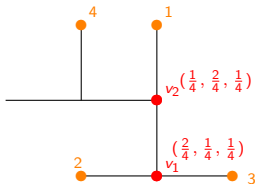
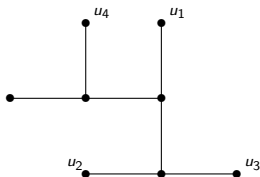


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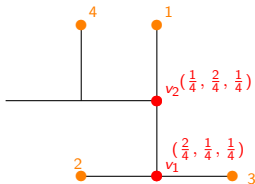
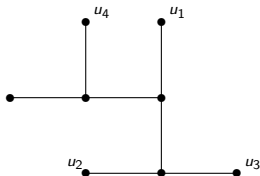


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Definition (Subtree mass convergence)

(T_n, c_n, μ_n) converges to (T, c, μ) in the sense of *convergence of sample subtree masses* if for every $m \in \mathbb{N}$ the vectors of masses branching off the branch points in the subtree spanned by a sample of size m converge.

Obvious inclusions

- Sample shape convergence and sample subtree masses convergence imply global convergence.
- Sample shape convergence implies sample subtree masses convergence.

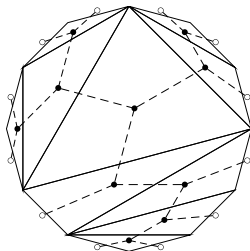
Theorem (Löhr & W. (2021))

- 1 *All three notions of convergence are equivalent on \mathbb{T}_2 .*
- 2 *\mathbb{T}_2 is compact.*

↪ Proof uses correspondence to **(sub-)triangulations of the circle**.

Triangulations of polygons and finite trees

[ALDOUS'94]



branch points = (open) triangles
edges connecting two vertices = separating side of the triangles
leaves = sides of the polygon

↪ Continuum limits (= triangulations of the circle) encode binary algebraic trees (without the measure); [CURIEN AND LE GALL (2011)], [CURIEN, HAAS, AND KORTCHEMSKI (2015)],...

Sub-triangulations of the circle

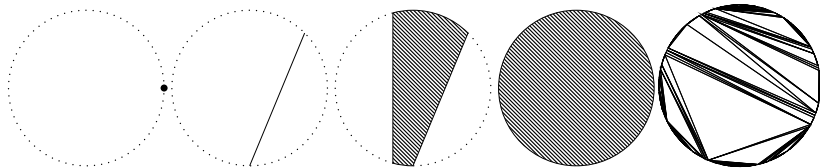
↷ encode also the measure and unify discrete and continuum trees

Definition ((sub-)triangulations; Aldous (1994), Löhner & W. (2021))

A closed subset $C \neq \emptyset$ of the closed disc \mathbb{D} is called a **sub-triangulation of the circle** if and only if the following two conditions hold:

(T1) $\text{conv}(C) \setminus C$ is the disjoint union of open interiors of triangles.

(T2) C is the union of non-crossing (non-intersecting except at endpoints), (possibly degenerated) closed straight line segments with endpoints in the circle $\mathbb{S} := \partial\mathbb{D}$.



Sub-triangulations of the circle

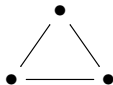
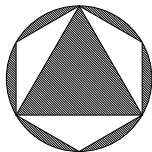
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↪ Aldous' original definition missed (T2) which can be shown to be equivalent for branch points to exist.



Remember: I am not a tree

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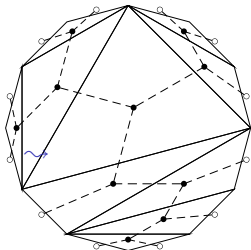
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Proposition (Löhrl & W. (2021))

\mathcal{T} and $\mathcal{T}^{\text{cont}}$ are closed in the space of all closed subsets of \mathbb{D} with respect to the Hausdorff metric and therefore **compact**.

From sub-triangulations to algebraic measure trees (2021)



branch points = (open) triangles
edges = sides of triangles
leaves = lie on circle

Measure can be also encoded.

mass on leaf = length on circle

Proposition (Löhr & W.)

There is a *surjective* map $\tau : \mathcal{T} \rightarrow \mathbb{T}_2$, which is *continuous* when \mathbb{T}_2 is equipped with the sample shape topology.

↪ From here one can conclude equivalence of the notions of convergence, compactness and metrizability of \mathbb{T}_2 .

Corollary

The sets of sample shape polynomials and of sample subtree mass polynomials are *convergence determining* for probability measures on \mathbb{T}_2 .

↪ *Stone-Weierstrass theorem*; polynomials closed under multiplication

Why is the result of interest?

- ① Using global convergence allows to exploit well-known results about Gromov-weak convergence.
 - ② Showing convergence of graph theoretic tree-valued MCs as the number of vertices tends to infinity simplifies if we have *compact state space*:
 - [LÖHR, MYTNIK & W., “Aldous chain on cladograms in the diffusion limit”, (2020)]
 - [NUSSBAUMER & W., “The algebraic α -Ford tree under evolution”, (ARXIV2022)]
 - [GAMBELIN, “The stable algebraic measure tree diffusion”, PART OF HIS PHD THESIS]
 - ③ The convergence of sample subtree mass tensor distributions allows to analyse the limit processes with stochastic analysis methods.
- ↪ Approach is already generalized to two-level algebraic measure trees: [NUSSBAUMER, TRAN VIET & W. (ARXIV2022)]

Many thanks!

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- Evans, Grübel & Wakolbinger; *"Doob-Martin boundary of Rémy tree growth chain"*, (2017)
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- Fisher & Zastrov; *"Combinatorial \mathbb{R} -trees as generalized Cayley graphs for fundamental groups of one-dimensional spaces"*, Geom. Dedicata, (2013)
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- Vapnik and Chervonenkis; *On the uniform convergence of relative frequencies of events to their probabilities*, Theor. Probability Appl. (1971)