

Robustness of spatial preferential attachment networks

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joint work with

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- robustness of the network under attack,
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Bollobás and Riordan defined a growing family of random graphs based on the preferential attachment paradigm and rigorously verified several of the conjectured emerging features.

The preferential attachment models of **Bollobás and Riordan** and of **Dereich and M.** are **locally tree-like** and have **very few short cycles**. Indeed, the key tool in the study of preferential attachment models is local approximation by branching processes. Real networks by contrast exhibit **clustering** and contain **many short cycles**.

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A plausible reason for the clustering in networks is the presence of **individual features** of the nodes such that similarity of features is an additional incentive to form links. We therefore propose a model in which preferential attachment is combined with **spatial structure** to address this. Similar models have been set up by **Flaxman, Frieze and Vera (2006)** and **Aiello, Bonato, Cooper, Janssen and Pralat (2009)**.

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- A node born at time t is connected by an edge to each existing node **independently** with probability

$$\varphi\left(\frac{t\rho}{f(k)}\right),$$

where

- k is the indegree of the older node at time t ,
- ρ is the distance of the nodes,
- $\varphi: [0, \infty) \rightarrow [0, 1]$ is a decreasing **profile function**,
- $f: \mathbb{N}_0 \rightarrow (0, \infty)$ is an increasing **attachment rule**.

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Conventions:

- We normalise φ so that $\int \varphi(|x|) dx = 1$.
- We assume $\gamma := \lim_{k \rightarrow \infty} \frac{f(k)}{k}$ exists and $0 < \gamma < 1$.

Suppose the graph G_{t-} is given, and a **vertex is born at time t** . Then, for each vertex in G_{t-} with indegree k , the probability that it is linked to the newborn vertex is equal to

$$\int \varphi \left(\frac{td(0, y)}{f(k)} \right) dy = \frac{f(k)}{t} 2 \int_0^{\frac{t}{2f(k)}} \varphi(x) dx \sim \frac{f(k)}{t}.$$

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Indegree processes of different vertices are **dependent**.

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Theorem 1 Jacob and M (2013)

The empirical indegree distributions μ_t converge in probability to a deterministic probability measure μ given by

$$\mu(k) = \frac{1}{1 + f(k)} \prod_{\ell=0}^{k-1} \frac{f(\ell)}{1 + f(\ell)} = k^{-(1+\frac{1}{\gamma})+o(1)},$$

i.e. the asymptotic indegree distribution is a **power law** with exponent

$$\tau = 1 + \frac{1}{\gamma}.$$

The empirical outdegree distribution converges to a light-tailed distribution, which does not influence the power law exponent.

For a finite graph G we define the **local clustering coefficient**

$$c^{\text{loc}}(v) := \frac{\#\text{triangles containing } v}{\#\text{adjacent edge pairs meeting at } v}$$

and the **average clustering coefficient** as

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Theorem 2 Jacob and M (2013)

The network $(G_t)_{t>0}$ is clustering in the sense that

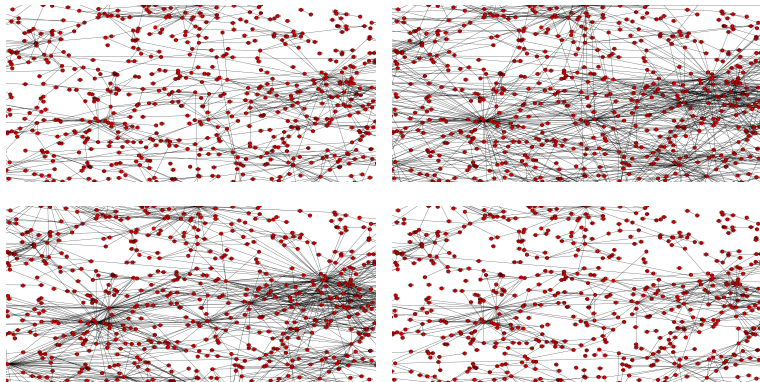
$$c^{\text{av}}(G_t) \rightarrow c_{\infty}^{\text{av}} > 0 \quad \text{in probability.}$$

Clustering coefficients

Suppose φ is regularly varying at infinity with **index** $-\delta$, for $\delta > 1$. The **parameter** δ controls the **probability of long edges** and quantifies the clustering; the **bigger** δ the **stronger the clustering**.

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Simulations with parameters (clockwise from top left) (a) $\gamma = 0.5$, $\delta = 2.5$,
(b) $\gamma = 0.75$, $\delta = 2.5$, (c) $\gamma = 0.5$, $\delta = 5$, (d) $\gamma = 0.75$, $\delta = 5$.

We now address the problem of **robustness of the network** $(G_t)_{t>0}$ under percolation. Let $C_t \subset G_t$ be the largest connected component in G_t and denote by $|C_t|$ its size. We say that the network has a **giant component** if C_t is of linear size or, more precisely, if

$$\lim_{\varepsilon \downarrow 0} \limsup_{t \rightarrow \infty} \mathbb{P} \left(\frac{|C_t|}{t} \leq \varepsilon \right) = 0.$$

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We write ${}^p G_t$ for the random subgraph of G_t obtained by **Bernoulli percolation** with retention parameter $p > 0$ on the vertices of G_t .

The network $(G_t)_{t>0}$ is said to be **robust** if, for any $p > 0$, the network $({}^p G_t)_{t>0}$ has a giant component.

Theorem 3 (Jacob and M. 2015)

The network $(G_t)_{t>0}$ is **robust** if $\gamma > \frac{\delta}{1+\delta}$ or equivalently $\tau < 2 + \frac{1}{\delta}$.

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- Robustness requires **strong preferential attachment** and **weak clustering** and can fail for any power-law exponent if the clustering is too strong. For example, the spatial preferential attachment model of **Aiello et al.(2009)** has too strong clustering and is **never robust**.

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- Robustness has also been shown by [Deijfen, van der Hofstad and Hooghiemstra \(2013\)](#) for a scale-free long range percolation model.

Let $C_t \subset G_t$ be the largest connected component in G_t . We say that the network has **no giant component** if C_t has sublinear size, i.e.

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- (a) if $\gamma < \frac{1}{2}$ or equivalently $\tau > 3$;
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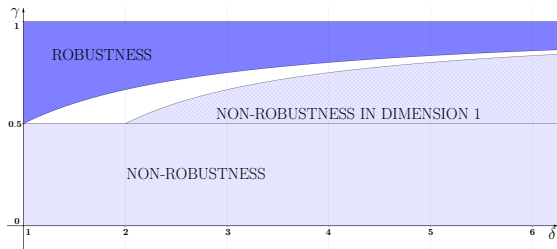
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- Robustness does not occur if the profile function φ is not heavy-tailed, i.e. as $\delta \rightarrow \infty$.
- We conjecture **non-robustness** for $\gamma < \frac{\delta}{\delta+1}$ or equivalently $\tau > 2 + \frac{1}{\delta}$.

Proof strategy for non-robustness

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- The network is **non-robust** if, for some $p > 0$ the percolated limit model pG^∞ has no infinite component.
- The **main problem** is that, if n is large, there is no easy upper bound for the probability that n distinct vertices x_1, \dots, x_n in G^∞ form a path $\{x_1 \leftrightarrow x_2 \leftrightarrow \dots \leftrightarrow x_n\}$.

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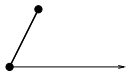
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- Two increasing events **occur disjointly** if the Poisson points can be divided into two subsets such that the first event holds if the points falling in the first subset are present, and the second event occurs if the points falling in the second subset are present.

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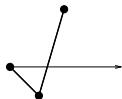
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- Two increasing events **occur disjointly** if the Poisson points can be divided into two subsets such that the first event holds if the points falling in the first subset are present, and the second event occurs if the points falling in the second subset are present.
- The **BK-inequality** of **van den Berg and Kesten (1985)** states that the probability of increasing events occurring disjointly is bounded by the probability of their product.

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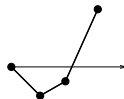
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- With this trick the path can be split into pieces which up to symmetry are **one of the following six types**.



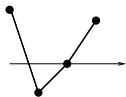
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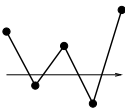
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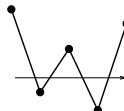
(iii)



(iv)



(v)



(vi)

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$$x_0 \leftrightarrow x_1 \leftrightarrow x_2,$$

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Now any vertex $z'_1 \in G^\infty$ younger than x_0 and x_2 but older than z_1 can only influence the indegree of either z_0 or z_2 at the birth time of z_1 , but never both. Hence $z_0 \leftrightarrow z_1 \leftrightarrow z_2$ being a quick path implies the disjoint occurrence of the events $\{z_0 \leftrightarrow z_1\}$ and $\{z_1 \leftrightarrow z_2\}$.

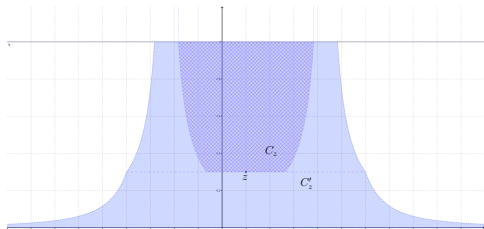
The construction of quick paths is **not using spatial information** and gives non-robustness only in the case $\tau > 3$. To show non-robustness in the case $\tau > 2 + \frac{1}{\delta-1}$ a refinement is needed.

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For a point z define a **region around z** and show that the typical number of vertices outside this region that are connected to z , or any other vertex in C_z , is small. Including only edges that straddle the boundary of the region in a **reduced quick path** improves the bound if $\delta > 2$.



- We define a **spatial preferential attachment model** in which every vertex has **individual features** represented by its position on the unit circle. New vertices attach to existing vertices with a probability favouring connections to vertices with similar features and high degrees. The resulting networks are **scale free** and exhibit **clustering**.

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- For sufficiently **strong preferential attachment** and sufficiently **weak clustering** the networks are **robust**.
- The **phase transition** between the robust and non-robust phase does **not occur at $\tau = 3$** , but at a smaller value depending on the clustering strength. This is a **new phenomenon**.
- The **proof of non-robustness** is based on an upper bound for the probability of a special class of paths in the network, called the **quick paths**. We use disjoint occurrence of events and the **BK inequality** to break up paths into short bits whose probabilities can be estimated.

Talks based on

- Spatial preferential attachment networks:
Power laws and clustering coefficients
Emmanuel Jacob and Peter Mörters.
Annals of Applied Probability. 25 (2015) 632-662.
- Robustness of scale-free spatial networks
Emmanuel Jacob and Peter Mörters.
Submitted for publication, arXiv:1504.00618

Thank you very much for your attention!