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On subsolutions to a semilinear elliptic problem

<u>ABSTRACT</u>: The relation between the existence of a subsolution for the problem $-\Delta u = f(u)$ with 0 — Dirichlet boundary value on a bounded domain and on a ball of R^N is considered. As a consequence a necessary condition for the existence of solutions when f changes sign is given.

1. INTRODUCTION AND STATEMENT OF RESULTS

In this paper we consider the following problem:

$$-\Delta u = f(u) \text{ in } \Omega,$$

$$u = 0 \quad \text{on } \partial\Omega,$$
(1.1)

where Ω is a bounded domain of $R^{\mbox{\it N}}$, N > 1, and the function f: R + R is assumed to be only continuous.

We call a function u $\mathsf{EC}(\bar{\Omega})$ a "subfunction on Ω " if the following differential inequality

$$\int_{\Omega} [u(-\Delta \phi) - f(u)\phi] dx \le 0$$
 (1.2)

holds for every $\phi \in D^+(\Omega)$, where $D^+(\Omega)$ consists of all nonnegative functions in $C_0^\infty(\Omega)$.

We shall make use of the following result (see [8, Lemma A.4, p. 105]): let u and v be subfunctions on Ω , then max(u,v) is also a subfunction on Ω . If the function u also satisfies

$$u \le 0 \text{ on } \partial\Omega,$$
 (1.3)

then we shall call u a "subsolution on Ω ". If the inequality in (1.2) (resp. (1.2) and (1.3)) is reversed, then we call u a superfunction on Ω (resp. a supersolution on Ω). A solution on Ω is a function u which is both a sub- and a supersolution on Ω . We shall use the following notation:

for
$$x_0 \in \mathbb{R}^{\mathbb{N}}$$
 and $R > 0$, $B(x_0,R) := \{x \in \mathbb{R}^{\mathbb{N}}; |x-x_0| < R\}$ and $B_R = B(0,R)$.

THEOREM 1: Let u be a subsolution on Ω satisfying \max_{Ω} u > 0. Then there exist R > 0 and a subsolution v on BR with \max_{Ω} v = \max_{Ω} u, satisfying:

- (i) v is positive on B_R and v = 0 on ∂B_R
- (ii) v is radially symmetric.

<u>REMARK</u>: The function v can even be chosen such that $|x| \rightarrow v(x)$ is non-increasing on [0,R]. As a consequence, we have

A first result in this direction was obtained by De Figueiredo in [6]. With additional regularity on f and for *positive* solutions, condition (1.4) has been proved to be necessary in Dancer and Schmitt [5]. See also for related results [2], [3], [9]. In the proof of Theorems 1 and 2, we avoid the use of a theorem of Gidas, Ni and Nirenberg [7], which requires the positivity of u and more regularity on f.

Concerning a partial converse of Theorem 1, we mention the following result [10]: Let v be a subsolution on B₁ satisfying max v > 0. Suppose either $f(0) \ge 0$ or Ω satisfies a uniform interior sphere condition [1]. Then there exist $\lambda > 0$ and $u \in C(\bar{\Omega})$ satisfying

$$\int_{\Omega} u(-\Delta \phi) dx \le \lambda \int_{\Omega} f(u) \phi \ dx, \text{ for every } \phi \in D^{+}(\Omega), \text{ max } u = \text{max } v,$$

$$u \text{ is positive on } \Omega, \text{ and}$$

$$u = 0 \text{ on } \partial\Omega.$$

$$(1.5)$$

If f(0) < 0 and Ω does not satisfy a uniform sphere condition, it may happen that the conclusion fails.

EXAMPLE: Let $f(u) = -\cos u$. Then if the boundary of Ω is of class C^3 , there exists a pair $(\lambda, u) \in \mathbb{R}^+ \times C^d(\overline{\Omega}) := \mathbb{R}^+ \times C^2(\Omega) \cap C^0(\overline{\Omega})$ satisfying

$$-\Delta u = \lambda f(u)$$
 in Ω ,
 $u = 0$ on $\partial \Omega$,
$$(1.6)$$

with u positive in Ω and max $u \in (\pi,3\pi/2)$ (see, for example, [3]). This is true in particular if Ω is the unit ball in R^N . However, it is shown in [8] that if Ω is a hypercube there is no pair $(\lambda,u) \in R^+ \times C^d(\bar{\Omega})$ satisfying (1.6), with u positive in Ω and max $u \in (\pi,3\pi/2)$. Since $3\pi/2$ is a supersolution of (1.6) for every $\lambda > 0$, there is no positive subsolution of (1.6) with maximum lying in $(\pi,3\pi/2)$ for every $\lambda > 0$. For a proof of this statement and for more results in this direction, we refer the reader to [8] and [10].

2. PROOFS

PROOF OF THEOREM 1: Let u be a subsolution on Ω satisfying max u > 0. Without loss of generality we may assume, by using a translation, that the maximum of u is achieved at the origin. Since Ω is bounded, we may also assume, by using Tietze's theorem, that the function u is the restriction on $\bar{\Omega}$ of some continuous function on R^N , nonpositive outside of Ω and zero outside of a ball large enough. We shall still denote the extended function by u. Define

$$u^*(r) = \max\{u(x); |x| = r\}$$
 for every $r \ge 0$.

Observe that \mathbf{u}^{\star} is continuous since the following inequality holds:

$$|u^*(r_1) - u^*(r_2)| \le \max_{|\theta|=1} |u(r_1\theta) - u(r_2\theta)|$$
 (2.1)

and u is uniformly continuous on $\mathbb{R}^{\mathbb{N}}$.

We also have

$$u^*(0) = u(0) = \max u = \max u^* > 0.$$

Denote by R the first zero of u*. Define

$$v(x) = u^*(|x|) \text{ for } |x| \in [0,R].$$

Then v is continuous on \bar{B}_R , positive on B_R , v = 0 on ∂B_R , \max_{B_R} v = \max_{Ω} u, and v is radially symmetric.

We shall prove that v is a subfunction on B_R , and therefore v satisfies all the required properties. By using partitions of unity and the compactness of the support of the test functions $_{\varphi}$'s, it is sufficient to prove that for every $x_0 \in B_R$ there is $r_0 > 0$ such that $B(x_0, r_0)$ lies in B_R and that v is a subfunction on $B(x_0, r_0)$. Let $x_0 \in B_R$ and $\alpha = v(x_0) > 0$. From the uniform continuity of u on R^N , one finds $r_0 > 0$ such that

$$|u(x) - u(y)| < \frac{1}{3}\alpha \text{ for } |x-y| < r_0, x,y \in \mathbb{R}^N.$$
 (2.2)

From (2.1), we also have

$$|u^*(s_1) - u^*(s_2)| < \frac{1}{3}\alpha \text{ for } |s_1 - s_2| < r_0, s_1, s_2 \ge 0.$$
 (2.3)

From (2.3) we get

$$u^{*}(r) > \frac{2}{2}\alpha > 0 \text{ for } |r - |x_{0}|| < r_{0}.$$
 (2.4)

One finds that $B(x_0,r_0)$ lies in B_R , since u^* is continuous and vanishes at R. Define

$$\Sigma = \{\theta \in R^N; |\theta| = 1\}$$
 and

$$\Sigma' = \{\theta \in \Sigma; |x_0|\theta \in \Omega \text{ and } d(|x_0|\theta,\partial\Omega) \ge r_0\}.$$
 (2.5)

Let $\theta \in \Sigma \setminus \Sigma'$ and $y \in B(|x_0|\theta,r_0)$, then it follows from (2.2) and the fact that $u \leq 0$ outside of Ω , that $u(y) < \frac{2}{3}\alpha$.

Recalling (2.4) we obtain

$$u^*(r) = \max \{u(r\theta); \theta \in \Sigma\} = \max\{u(r\theta); \theta \in \Sigma'\} \text{ for } |r-|x_0|| < r_0.$$

We can even choose a countable dense subset $\Sigma^{\text{\tiny{II}}}$ of $\Sigma^{\text{\tiny{I}}}$ such that

$$u^*(r) = \max\{u(r\theta); \theta \in \Sigma''\} \text{ for } |r-|x_0|| < r_0.$$

Denote by $\theta_0, \theta_1, \theta_2, \ldots, \theta_n, \ldots$ the elements of Σ ". It follows from the definition of Σ ', (2.5), that $B(|x_0|\theta_n, r_0) \subseteq \Omega$ for all $n \in \mathbb{N}$. Moreover, u is a subfunction on $B(|x_0|\theta_n, r_0)$ $n \in \mathbb{N}$. For every $n \in \mathbb{N}$, there is a rotation R_n which maps $B(x_0, r_0)$ onto $B(|x_0|\theta_n, r_0)$ and such that

$$v(x) = \max\{u(R_n x); n \in \mathbb{N}\}, x \in B(x_0, r_0).$$

From the rotation invariance in (1.2), it follows that the functions w_n defined by $w_n(x) = u(R_n x)$ are subfunctions on $B(x_0, r_0)$. Then

$$v_n = \max\{w_k; 0 \le k \le n\}$$

is an increasing sequence of subfunctions on $B(x_0,r_0)$ and by Dini's theorem $v = \sup_{n \geq 0} v_n = \lim_{n \to \infty} v_n$ is a subfunction on $B(x_0,r_0)$. This completes the proof of Theorem 1. \square

<u>PROOF OF THEOREM 2</u>: Let u be a subsolution of Ω with ρ = max u > 0. Let R > 0 and let v be the subsolution on B_R from Theorem 1.

Suppose that there is s \in [0, ρ) such that $\int_S^\rho f(t) \ dt \le 0$. We will obtain a contradiction. For n = 1,2,..., define

$$f_n(t) = \begin{cases} f(t) & \text{for } t \leq \rho, \\ \\ f(\rho)[1+n(\rho-t)] & \text{for } t > \rho. \end{cases}$$

Then $f_n \in C(R)$ and $f_n(\rho + 1/n) = 0$. Then v is a radially symmetric subsolution to the problem

$$(P_n) \qquad \begin{cases} -\Delta u = f_n(u) & \text{on } B_R, \\ u = 0 & \text{on } \partial B_R, \end{cases}$$

and ρ + 1/n is a radially symmetric supersolution of (P_n) satisfying $v \le \rho$ + 1/n. By using a result of [4], there exists a solution u_n of (P_n),

satisfying $v \le u_n^{\le \rho} + 1/n$. By using a slight modification of the argument of [4], namely by applying the Schauder fixed-point theorem on the space of continuous functions on \bar{B}_R which are radially symmetric, one can assume that u_n is radially symmetric. Then we obtain, since $u_n \in C^2(\bar{B}_R)$,

$$-u_{n}^{"}(r) - \frac{\mathbb{N}-1}{r} u_{n}^{"}(r) = f_{n}(u_{n}(r)), \quad r \in [0,R],$$

$$u_{n}^{"}(r) = 0, \qquad u_{n}(R) = 0.$$
(2.6)

By integration, we obtain

$$\int_{u_{n}(r)}^{u_{n}(0)} f_{n}(s) ds \ge (N-1) \int_{0}^{r} \frac{1}{s} u_{n}^{2}(s) ds, r \in [0,R].$$
 (2.7)

Since the functions $f_n(u_n)$ are uniformly bounded on [0,R], it follows from (2.6) that the functions u_n , u_n' and u_n'' are uniformly bounded on [0,R]. For every $n \in \mathbb{N}$, there exists $r_n \in [0,R]$ such that $u_n(r_n) = s$. There exist a function $\bar{u} \in C^1[0,R]$, $\bar{r} \in [0,R]$ and a subsequence which we still denote by (u_n,r_n) such that u_n converges to \bar{u} in $C^1[0,R]$ and r_n to \bar{r} .

Since $\rho > s = \lim_{n \to \infty} u_n(r_n) = \bar{u}(\bar{r})$ and $\bar{u}(0) = \rho$, we have $\bar{r} > 0$. From (2.7), we obtain

$$\int_0^{\overline{r}} \frac{1}{t} \overline{u'}^2(t) \ dt = \lim_{n \to \infty} \int_0^{r_n} \frac{1}{t} \, u_n'^2(t) \ dt = 0.$$

Hence $\bar{u}(t) = \rho$ on $[0,\bar{r}]$, and $s = \bar{u}(\bar{r}) = \rho$, a contradiction. This completes the proof of Theorem 2. \Box

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